

UNIVERSITI TUN HUSSEIN ONN MALAYSIA

FINAL EXAMINATION SEMESTER II SESSION 2020/2021

COURSE NAME

ENGINEERING MATHEMATICS II

COURSE CODE

BDX 10502

PROGRAMME CODE :

BDX

EXAMINATION DATE :

JULY 2021

DURATION

2 HOURS

INSTRUCTION QUESTIONS

ANSWER **FOUR (4)** FROM FIVE (5)

QUESTIONS ONLY

TERDUKA

THIS QUESTION PAPER CONSISTS OF EIGHT (8) PAGES

Q1 (a) Evaluate the Lagrange Interpolating polynomial for data f(0) = 1, f(2) = -1, f(4) = -1 and f(6) = 1. Hence, evaluate f(3), f(5) and f(6.5), if applicable.

(25 marks)

Q2 (a) Convert to spherical coordinates and solve

$$\int_0^3 \int_0^{\sqrt{9-x^2}} \int_{-\sqrt{9-x^2-y^2}}^{\sqrt{9-x^2-y^2}} (x^2 + y^2 + z^2) dz dy dx.$$

(12 marks)

(b) Solve the volume of the solid G, that lies between the two cylinders $x^2 + y^2 = 1$ and $x^2 + y^2 = 9$ bounded above by paraboloid $z = 12 - x^2 - y^2$ and below by xyplane.

(13 marks)

Q3 (a) A periodic function f(x) is defined by

$$f(x) = x, \qquad -1 < x < 1$$

and

$$f(x) = f(x+2)$$

i) Sketch the graph of the function over -3 < x < 3

(6 marks)

ii) Evaluate the Fourier coefficients corresponding to the function.

(10 Marks)

iii) Solve the corresponding Fourier series.

(9 Marks)

Q4 Solve the system of linear equations below by using Thomas method

$$\begin{pmatrix} 1 & 2 & 0 & 0 \\ 3 & 4 & 5 & 0 \\ 0 & 6 & 7 & 8 \\ 0 & 0 & 10 & 11 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 2 \\ 3 \end{pmatrix}$$

Given a system of response following the function $y = x^6 - x - 1$. Solve the stable condition (zero) of the system in the range [1,2] using Bisection method. Iterate until the tolerance error $(b-a)/2 \le 0.005$

(25 marks)

-END OF QUESTION -



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FORMULA

Polar Coordinates:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$x^2 + v^2 = r^2$$

where $0 \le \theta \le 2\pi$

$$\iint_{\mathbb{R}} f(x, y) dA = \iint_{\mathbb{R}} f(r, \theta) r dr d\theta$$

Cylindrical Coordinates:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

where $0 \le \theta \le 2\pi$

$$\iiint\limits_G f(x, y, z)dV = \iiint\limits_G f(r, \theta, z)rdzdrd\theta$$

Spherical Coordinates:

$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

$$\rho^2 = x^2 + v^2 + z^2$$

where $0 \le \phi \le \pi$ and $0 \le \theta \le 2\pi$

$$\iiint\limits_{G} f(x, y, z) dV = \iiint\limits_{G} f(\rho, \phi, \theta) \rho^{2} \sin \phi d\rho d\phi d\theta$$

In 2-D: Lamina

Given that $\delta(x, y)$ is a density of lamina

Mass,
$$m = \iint_{R} \delta(x, y) dA$$
, where

Moment of Mass

a. About x-axis,
$$M_x = \iint_R y \delta(x, y) dA$$

b. About y-axis,
$$M_y = \iint_{\mathbb{R}} x \delta(x, y) dA$$



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Centre of Mass

Non-Homogeneous Lamina:

$$(\overline{x}, \overline{y}) = \left(\frac{M_y}{m}, \frac{M_x}{m}\right)$$

Centroid

Homogeneous Lamina:

$$\overline{x} = \frac{1}{Area \ of} \iint_{R} x dA \text{ and } \overline{y} = \frac{1}{Area \ of} \iint_{R} y dA$$

Moment Inertia:

a.
$$I_{y} = \iint x^{2} \delta(x, y) dA$$

b.
$$I_x = \iint_{\mathcal{D}} y^2 \delta(x, y) dA$$

b.
$$I_{y} = \iint_{R} x^{2} \delta(x, y) dA$$

$$I_{x} = \iint_{R} y^{2} \delta(x, y) dA$$

$$I_{x} = \iint_{R} (x^{2} + y^{2}) \delta(x, y) dA$$

$$I_{o} = \iint_{R} (x^{2} + y^{2}) \delta(x, y) dA$$

In 3-D: Solid

Given that $\delta(x, y, z)$ is a density of solid

Mass,
$$m = \iiint_G \delta(x, y, z) dV$$

If $\delta(x, y, z) = c$, where c is a constant, $m = \iiint_C dA$ is volume.

Moment of Mass

a. About yz-plane,
$$M_{yz} = \iiint_G x \delta(x, y, z) dV$$

b. About xz-plane,
$$M_{xz} = \iiint_C y \delta(x, y, z) dV$$

c. About xy-plane,
$$M_{xy} = \iiint_C z \delta(x, y, z) dV$$

Centre of Gravity

$$(\overline{x}, \overline{y}, \overline{z}) = \left(\frac{M_{yz}}{m}, \frac{M_{xz}}{m}, \frac{M_{xy}}{m}\right)$$

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Moment Inertia

a. About x-axis,
$$I_x = \iiint_G (y^2 + z^2) \delta(x, y, z) dV$$

b. About y-axis,
$$I_y = \iiint_G (x^2 + z^2) \delta(x, y, z) dV$$

c. About z-axis,
$$I_z = \iiint_G (x^2 + y^2) \delta(x, y, z) dV$$

Directional Derivative

$$D_u f(x, y) = (f_x \mathbf{i} + f_y \mathbf{j}) \cdot \mathbf{u}$$

Del Operator

$$\nabla = \frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k}$$

Gradient of $\phi = \nabla \phi$

Let $\mathbf{F}(x, y, z) = M\mathbf{i} + N\mathbf{j} + P\mathbf{k}$, hence,

The **Divergence** of $\mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$

The **Curl** of $\mathbf{F} = \nabla \times \mathbf{F}$

$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix}$$
$$= \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \mathbf{i} - \left(\frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) \mathbf{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \mathbf{k}$$

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Let C is smooth curve defined by $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$, hence,

The Unit Tangent Vector,
$$T(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$$

The Principal Unit Normal Vector,
$$N(t) = \frac{T'(t)}{\|T'(t)\|}$$

The **Binormal Vector**, $\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$

Curvature

$$\kappa = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|}$$

Radius of Curvature

$$\rho = \frac{1}{\kappa}$$

Green's Theorem

$$\iint\limits_{C} M dx + N dy = \iint\limits_{R} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

Gauss's Theorem

$$\iint_{S} \mathbf{F} \cdot \mathbf{n} dS = \iiint_{G} \nabla \cdot \mathbf{F} dV$$

Stoke's Theorem

$$\iint_{C} \mathbf{F} \cdot dr = \iint_{S} (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS$$

Arc Length

If
$$\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$$
, $t \in [a,b]$, hence, the arc length,

$$s = \int_{a}^{b} || \mathbf{r}'(t) || dt = \int_{a}^{b} \sqrt{[x'(t)]^{2} + [y'(t)]^{2} + [z'(t)]^{2}} dt$$

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Total Differential

For function z = f(x, y), the total differential of z, dz is given by:

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$$

Relative Change

For function z = f(x, y), the relative change in z is given by:

$$\frac{dz}{z} = \frac{\partial z}{\partial x} \frac{dx}{z} + \frac{\partial z}{\partial y} \frac{dy}{z}$$

Implicit Differentiation

Suppose that z is given implicitly as a function z = f(x, y) by an equation of the form F(x, y, z) = 0, where F(x, y, f(x, y)) = 0 for all (x, y) in the domain of f, hence,

$$\frac{\partial z}{\partial x} = -\frac{F_x}{F_z}$$
 and $\frac{\partial z}{\partial y} = -\frac{F_y}{F_z}$

Extreme of Function with Two Variables

$$D = f_{xx}(a,b)f_{yy}(a,b) - [f_{xy}(a,b)]^{2}$$

- a. If D > 0 and $f_{xx}(a,b) < 0$ (or $f_{yy}(a,b) < 0$) f(x,y) has a local maximum value at (a,b)
- b. If D > 0 and $f_{xx}(a,b) > 0$ (or $f_{yy}(a,b) > 0$) f(x,y) has a local minimum value at (a,b)
- c. If D < 0f(x, y) has a saddle point at (a, b)
- d. If D = 0The test is inconclusive

Surface Area

Surface Area
$$= \iint_{R} dS$$
$$= \iint_{R} \sqrt{(f_{x})^{2} + (f_{y})^{2} + 1} dA$$