



UNIVERSITI TUN HUSSEIN ONN MALAYSIA

FINAL EXAMINATION
SEMESTER I
SESSION 2014/2015

COURSE NAME : MECHANICS PHYSICS
COURSE CODE : BWC 10103
PROGRAMME : 1 BWC
EXAMINATION DATE : DECEMBER 2014 / JANUARY 2015
DURATION : 3 HOURS
INSTRUCTION : 1. ANSWER **ALL** QUESTIONS IN SECTION A
2. ANSWER **THREE (3)** QUESTIONS ONLY IN SECTION B

THIS QUESTION PAPER CONSISTS OF NINE (9) PAGES

SECTION A

- Q1** (a) What is the different between Lagrangian and Hamiltonion mechanics? (4 marks)
- (b) Consider a mass-spring system is moving in one dimension parameterised by the coordinate x . The particle is subjected to a conservative force whose potential is $U(x)$ and $K(v)$.
- (i) Write down the Lagrangian of the system, $L(x, v)$. (2 marks)
- (ii) Write down the Lagrange equations for the system described in Q(b)(i), and use them to show that the particle acceleration, a is equal to $-\frac{k}{m}x$ (8 marks)
- (c) Consider the motion of a particle of mass m with one degree of freedom parameterised by a coordinate x in a potential $V(x)$. Explain how the Hamiltonian $H(p, x)$ is obtained from the Lagrangian, and write down its expression. (6 marks)
- Q2** (a) A sphere is rotating with angular velocity, ω at coordinate point, $\mathbf{r} = (5, 5)$ in two dimensional xy -axis system. In this coordinates system, the sphere moves at a velocity, v then accelerates with a magnitude of a . If the coordinates frame is rotated by 45° counter-clockwise, determine,
- (i) a new coordinates, \mathbf{r}' for the sphere in the rotating coordinates system. (2 marks)
- (ii) tangential velocity, v' in the rotating coordinates system. (2 marks)
- (iii) tangential acceleration, a' in the rotating coordinates system. (2 marks)
- (b) Two asteroids, X and Y of equal masses of $M = 3.5 \times 10^{18}$ kg are located 3.00 km apart as shown in Figure **Q2(b)**. The gravitational constant, $G = 6.674 \times 10^{-11} \text{N}(\text{m}/\text{kg})^2$. What is the net gravitational force of the spaceship with mass $m = 2.50 \times 10^7$ kg when it is located
- (i) at point A? (4 marks)
- (ii) at point B? (4 marks)
- (c) A satellite, S moves around a planet, P in an elliptical orbit as shown in Figure **Q2(c)**. What is the ratio of the speed of the satellite between point a and point b ? (6 marks)

SECTION B

Q3 (a) Three field quantities are given by

$$\begin{aligned} P &= 2\mathbf{a}_x - \mathbf{a}_z \\ Q &= 2\mathbf{a}_x - \mathbf{a}_y + 2\mathbf{a}_z \\ R &= 2\mathbf{a}_x - 3\mathbf{a}_y + \mathbf{a}_z \end{aligned}$$

Determine,

- (i) $(P + Q) \times (P - Q)$ (2 Marks)
- (ii) $Q \cdot R \times P$ (2 marks)
- (iii) $\sin \theta_{QR}$ (2 marks)
- (b) Write the rectangular coordinate location $A(3, 4, 2)$ in the cylindrical coordinate system. (4 marks)
- (c) A function of ϕ is given by, $\phi = x^2y - xz^3$. Find the gradient of this function, $\nabla\phi$ (4 marks)
- (d) Find a unit vector normal to the surface, $x^2y + xz = 2$ at the point $(1, -1, 1)$ (6 marks)

Q4 (a) A particle with a mass, m moves along a line so that at any time t its position is given by $x(t) = 2\pi t + \sin(2\pi t)$

- (i) Write an expression for the velocity $v(t)$ of the particle. (2 marks)
- (ii) Write an expression for the acceleration $a(t)$ (2 marks)
- (b) Under a specific force field, F , a particle of mass, $m = 3$ kg moves along a space curve with a position vector, r given as a function of time, t by,
 $r = (t^2 - 2t)\mathbf{i} + (t^3 + 3t^2)\mathbf{j} - 5t^2\mathbf{k}$
 Find,
- (i) the vector unit of the momentum for the particle, P (2 marks)
- (ii) the vector unit of the force field, F (2 marks)

- (c) The force, F acting on a particle are $(6\mathbf{i} + 2\mathbf{j} + 3\mathbf{k})$, $(3\mathbf{i} - 2\mathbf{j} + 6\mathbf{k})$ and $(2\mathbf{i} - 3\mathbf{j} - 6\mathbf{k})$. The particle is displaced from $(5\mathbf{i} - \mathbf{j} - \mathbf{k})$ to $(2\mathbf{i} - \mathbf{j} - 3\mathbf{k})$. Find,
- the resultant force, F applied to this particle. (4 marks)
 - the displacement of this particle, r . (4 marks)
 - the work, W to move this particle. (4 marks)

- Q5** (a) A particle performs simple harmonic motion with a period of 16 s. At time $t = 2$ s, the particle passes through the origin, while at $t = 4$ s, its velocity, v is 4 ms^{-1} . Show that the amplitude of the motion is $\frac{32\sqrt{2}}{\pi}$. (6 marks)
- (b) The block, having a mass of 7.5 kg, is immersed in a liquid as shown in Figure **Q5(b)**. The damping force acting on the block has a magnitude of $F = (12v)$ N, where v is the velocity of the block in ms^{-1} . If the block is pulled down 0.24 m and released from rest, determine the position of the block, x as a function of time, t . The spring constant, k is 600 Nm^{-1} . Consider positive displacement to be downward. (6 marks)
- (c) A mass-spring system is oscillated vertically under damped simple harmonic motion with natural angular frequency, ω as show in Figure **Q5(c)**. As a maximum external force, F_{max} is applied to the system, its driving angular frequency, ω_d is reduced twice of its natural angular frequency, ω .
- Determine a driving force, F_d of the system. (4 marks)
 - Write the applied force, F as a function of time, t (4 marks)

- Q6** (a) The rotational inertia of an object shown in Figure **Q6 (a)** depends not only on its mass distribution but also on the location of the axis of rotation.
- Show that the moment of inertia of a uniform hollow cylinder of inner radius R_1 , outer radius R_2 , and mass M , is $I = \frac{1}{2} M(R_1^2 + R_2^2)$, if the rotation axis is through the center along the axis of symmetry. (10 marks)
 - Obtain the moment of inertia for a solid cylinder. (2 marks)

- (b) A small child runs and jumps onto a merry-go-round which has a moment of inertia, I_0 about its axis of rotation is shown in Figure **Q6 (b)**. The child has mass, m and is initially moving with velocity, v , grabs onto a bar attached to the plate which is a distance, R from the center of the merry-go-round. The merry-go-round was initially not rotating. Assume that the child is running tangential to the merry-go-round before jumping on as shown. What fraction of the initial kinetic energy of the running child remains in the final system (i.e. what is KE_f/KE_i)? Give your answer in terms of I_0 , m , v , R .

(8 marks)

- Q7** (a) A system that is rotationally imbalanced will not have its angular momentum and angular velocity vectors in the same direction shown in Figure **Q7(a)**. A torque is required to keep an unbalanced system rotating. Determine the magnitude of the net torque, τ_{net} needed to keep the illustrated system turning.

(12 marks)

- (b) A baseball of mass 0.15 kg is initially traveling horizontally at 50 m/s. It is struck by a bat, after which the baseball is still travelling horizontally but in exactly the opposite direction from its initial motion at a speed of 40 m/s. Consider the collision of the bat and the ball which is shown in Figure **Q7 (b)**. Assume that before the collision, the bat is moving in a horizontal circle at an angular velocity of ω rad/s. Assume that the player holding the bat exerts no torque. The bat has a moment of inertia of 0.30 kgm^2 about the pivot and the ball hits at a point that is 80 cm away from the pivot. After the collision, the bat is still swinging in the same direction around the same pivot but with a reduced angular velocity of 0.35ω . Find the numerical value of ω .

(8 marks)

-END OF THE QUESTION-

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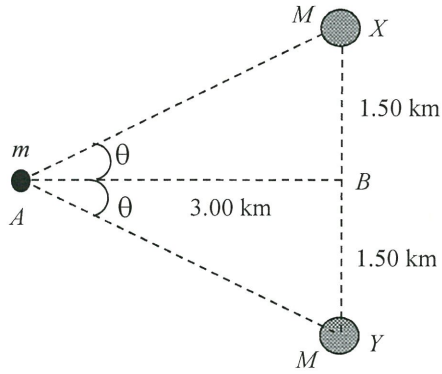


FIGURE Q2(b)

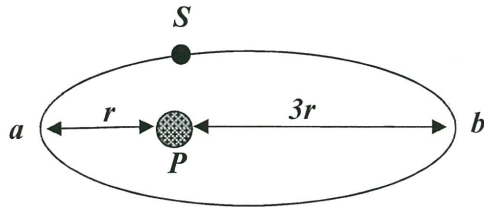


FIGURE Q2(c)

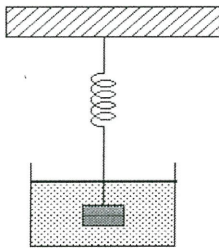


FIGURE Q5(b)

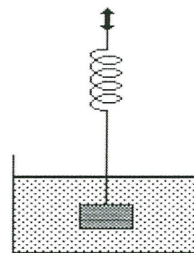


FIGURE Q5(c)

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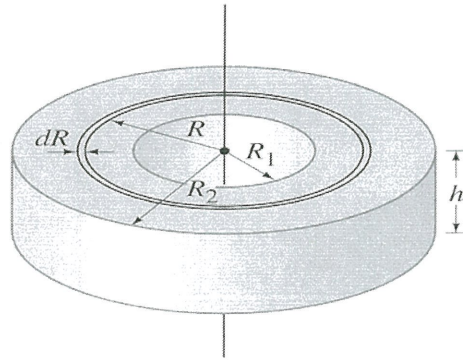


FIGURE Q6(a)

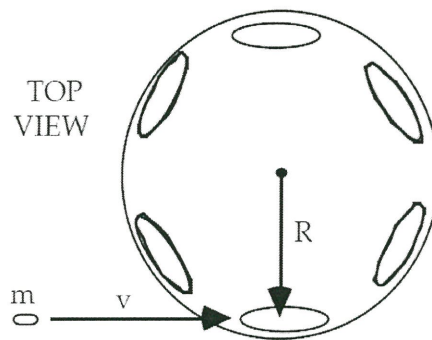


FIGURE Q6(b)

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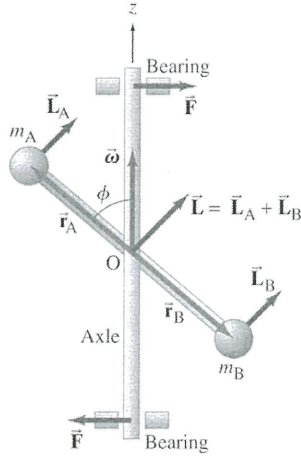


FIGURE Q7(a)

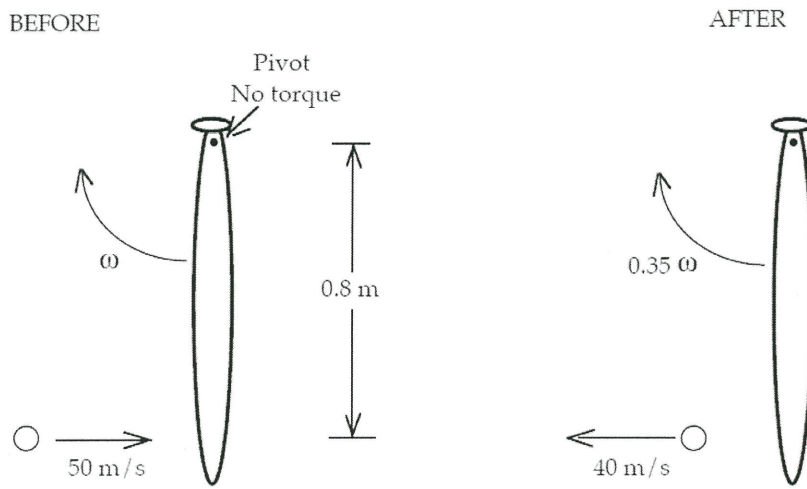


FIGURE Q7(b)

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LIST OF FORMULA

$L = K - U$	$\frac{d}{dt} \left(\frac{\partial L}{\partial v} \right) - \frac{\partial L}{\partial x} = 0$	$\frac{dx}{dt} = \frac{\partial H}{\partial p}$	$\frac{dp}{dt} = -\frac{\partial H}{\partial x}$
$v = v' + \omega r'$ $a = a' + 2\omega v' + (d\omega/dt)r' + \omega^2 r'$		$F = -G \frac{m_1 m_2}{R^2}$	
$A \cdot B = AB \cos \theta_{AB}$		$A \times B = AB \sin \theta_{AB}$	
$x = \rho \cdot \sin(\varphi) \cdot \cos(\theta)$ $y = \rho \cdot \sin(\varphi) \cdot \sin(\theta)$ $z = \rho \cdot \cos(\varphi)$ $\rho^2 = x^2 + y^2 + z^2$ $\tan\left(\theta = \frac{y}{x}\right)$ $\cos(\varphi) = \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \frac{z}{\rho}$		$\nabla f(x, y) = \frac{\partial f}{\partial x} i + \frac{\partial f}{\partial y} j + \frac{\partial f}{\partial z} k$ $\hat{n} = \frac{A}{ A }$	
$\frac{d}{dx}(\sin x) = \cos(x)$		$\frac{d}{dx}(\cos x) = -\sin(x)$	
$F = ma$		$F = -kx$	
$x(t) = A \cos(\omega t + \phi)$		$\omega = \sqrt{\frac{k}{m}}$	
$F = -kx - bv = ma$		$x(t) = x_o \cos\left(\sqrt{\frac{k}{m}} t\right)$	
$x(t) = A e^{-(b/2m)t} \cos(\omega' t + \phi)$ $F(t) = F_{\max} \cos(\omega_d t)$		$y = y_o + y_{o_y} t + \frac{1}{2} a_y t^2$	
$x = x_o + v_{o_x} t + \frac{1}{2} a_x t^2$ $X_{cm} = \frac{\sum m_i X_i}{\sum m_i}$, $Y_{cm} = \frac{\sum m_i Y_i}{\sum m_i}$, $Z_{cm} = \frac{\sum m_i Z_i}{\sum m_i}$		$I_{\text{sphere}} = \frac{2}{5} MR^2$ $I_{\text{rod}} = \frac{1}{3} ML^2$ $L = I\omega$, $\tau = F \times r$	
$r = xi + yj + zk$ $v = \frac{dr}{dt} i + \frac{dr}{dt} j + \frac{dr}{dt} k$ $a = \frac{dv}{dt} i + \frac{dv}{dt} j + \frac{dv}{dt} k$		$v = \omega r$ $a = \omega^2 r$ $T = \frac{2\pi}{\omega}$	
$\rho = \frac{m}{V}$		$KE = \frac{1}{2} mv^2$	
$\tau_{\text{net}} = \frac{dL}{dt}$		$I = \int R^2 dm$	